

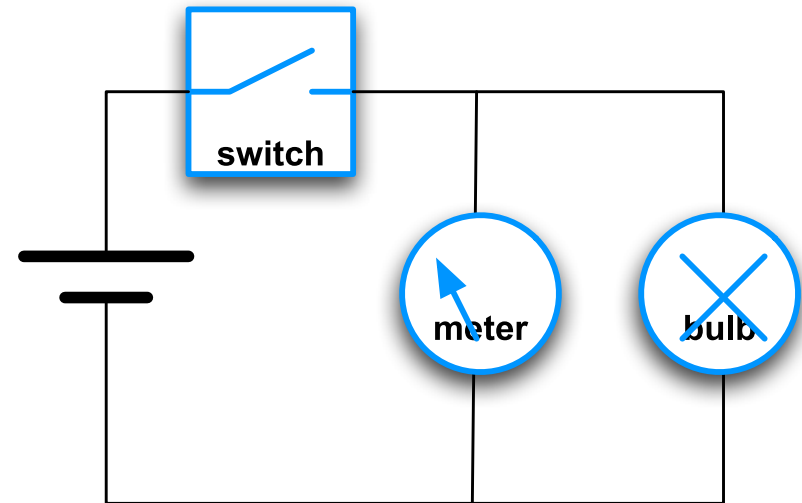
Symbolic Model Checking of Logics with Actions

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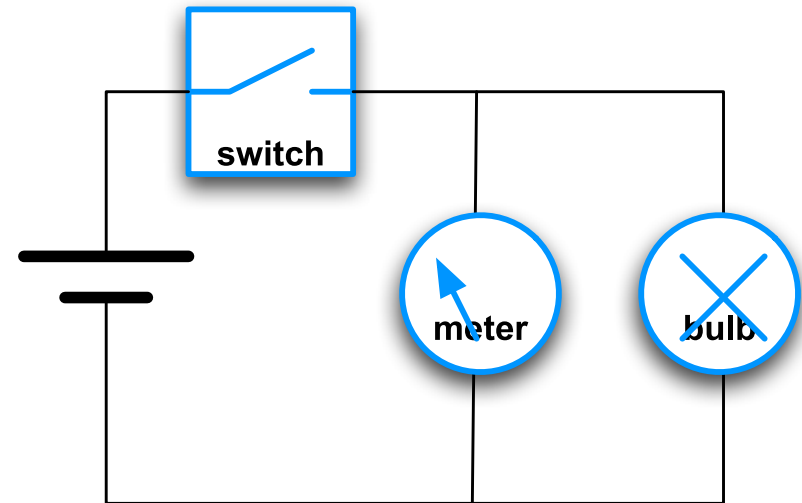
An Observable System

- An observable system
 - Electric circuit
- Hidden **state**
 - Bulb and meter can fail
- Visible **observations**
 - Read the meter, see the light



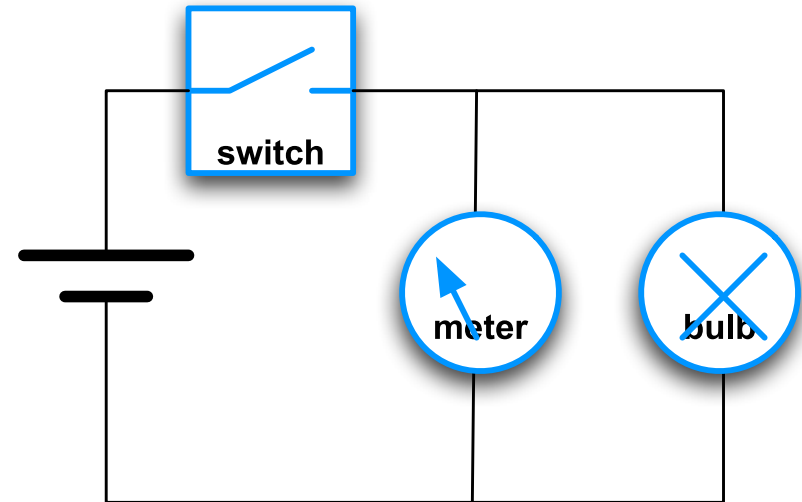
Diagnosis

- **Diagnosis:** from (history of) observations, infer state
 - Q: If there is no light and the meter reads zero, is there a current?
 - A: Maybe, if the meter is broken and the bulb has a short



Diagnosability

- **Diagnosability:**
diagnosis is possible (up to desired precision, assuming context, ...)
 - Q: Can I safely know when there is a short?
 - A: Yes, assuming single failures



From Diagnosability to Knowledge

- A condition F (fault) can be **diagnosed**
iff
an **agent** preceiving the observations (the diagnoser)
always **knows** whether F holds or not
- In epistemic temporal logic CTLK:

$$AG (K_D F \vee K_D \neg F)$$

where D is the diagnoser

From Knowledge to Actions

- In epistemic logic, agent A **knows** a fact ϕ
iff
 ϕ is true in any possible state (world) consistent with A 's knowledge
- Formalized as an **epistemic accessibility** (equivalence) relation \sim_A between states that are indistinguishable by A
- We obtain a system with several transition relations $\langle \mathcal{S}, \mathcal{S}_0, \rightarrow, \sim_{A_1}, \dots, \sim_{A_n} \rangle$ for n agents
- Or equivalently, a **labelled** transition system $\langle \mathcal{S}, \mathcal{S}_0, \mathcal{A}, \xrightarrow{a} \rangle$, where $\mathcal{A} = \{T, A_1, \dots, A_n\}$

Model-Checking Diagnosability

- Custom diagnosability checker by Pecheur [MOCHART02,IJCAI03]
 - Uses NuSMV as back-end
 - **Idea: try epistemic approach instead?**
- Custom CTLK checker by Raimondi [TACAS06]
 - BDD-based, directly on interpreted systems
 - Very rudimentary modelling language
 - **Idea: use NuSMV instead?**
- Extend SMV to actions, then to CTLK
 - **This talk**

Outline

- Mixing states and actions: ARCTL
- Model checking of ARCTL
- ARCTL in SMV (two takes)
- Application to CTLK and experiments
- Related work, summary, perspectives

State-Based Temporal Logic

- The “classical” temporal logic
- Interpreted over executions of state machines, (unlabelled) transition systems
 - Atoms \mathcal{P}_S are interpreted on **states**
 - **Kripke structure** (KS) $\langle \mathcal{S}, \mathcal{S}_0, \mathcal{R}, \mathcal{V} \rangle$, where $\mathcal{R} \subseteq \mathcal{S} \times \mathcal{S}$ and $\mathcal{V} : \mathcal{S} \rightarrow 2^{\mathcal{P}_S}$
- LTL, **CTL**, CTL*, μ -calculus, etc.
- Example: $AG (request \Rightarrow AF response)$

Action-Based Temporal Logic

- Variant from the process algebra world
- Interpreted on **labelled** transitions systems
 - Atoms are **actions** (i.e. transition labels)
 - **labelled transitions system** (LTS) $\langle \mathcal{S}, \mathcal{S}_0, \mathcal{A}, \mathcal{T} \rangle$,
where $\mathcal{T} \subseteq \mathcal{S} \times \mathcal{A} \times \mathcal{S}$
- No atoms on states; states are “not visible” (behavioural view)
- **Action-CTL** (ACTL) [deNicola-Vaandrager], ACTL*, Hennessy-Milner, etc.
- Example: $AG_{true} (\neg EX_{request} EG_{\neg response} true)$

Mixing States and Actions

- Three generalizations:
 - Allow arbitrary atoms \mathcal{P}_A interpreted over A
 - Allow both state and action atoms
 - Allow finite full-paths (i.e. sink states)
- **Mixed transition systems** (MTS) $\langle \mathcal{S}, \mathcal{S}_0, \mathcal{A}, \mathcal{T}, \mathcal{V}_S, \mathcal{V}_A \rangle$, where
 - $\mathcal{T} \subseteq \mathcal{S} \times \mathcal{A} \times \mathcal{S}$
 - $\mathcal{V}_S : \mathcal{S} \rightarrow 2^{\mathcal{P}_S}$
 - $\mathcal{V}_A : \mathcal{A} \rightarrow 2^{\mathcal{P}_A}$
- Contains LTS and KS as sub-structures

Action-Restricted CTL

- To support CTLK, we want to combine different transition/accessibility relations $\rightarrow, \sim_{A_1}, \dots, \sim_{A_n}$ into a single labelled transition relation over alphabet $\mathcal{A} = \{T, A_1, \dots, A_n\}$
- Correspondingly, we want to extend CTL so that temporal operators can be **restricted** to a given set of (or condition on) actions
 - e.g. over all T -paths, ϕ holds globally
- **Action-Restricted CTL** (ARCTL) generalizes path quantifiers A, E into A_α, E_α restricted to α -paths

ARCTL Semantics

- Given a mixed transition system \mathcal{M} , let
 - $\Pi(s)$ the set of (finite or infinite) full-paths of \mathcal{M} from s
 - α a propositional formula over \mathcal{P}_A
 - $\mathcal{M}|_\alpha$ the restriction of \mathcal{M} to α -actions
 - $\Pi|_\alpha(s)$ the set of full-paths of $\mathcal{M}|_\alpha$ from s
- For a path formula γ , we have
 - $s \models A_\alpha \gamma$ iff $\forall \pi \in \Pi|_\alpha(s) \cdot \pi \models \gamma$
 - $s \models E_\alpha \gamma$ iff $\exists \pi \in \Pi|_\alpha(s) \cdot \pi \models \gamma$

(full formal definitions in the paper)

ARCTL Properties and Remarks

- Obviously $E_{true}\gamma \equiv E\gamma$ and $A_{true}\gamma \equiv A\gamma$
- In general $\Pi|_{\alpha}(s) \not\subseteq \Pi(s)$ and thus $E_{\alpha}\gamma \not\Rightarrow E\gamma$
 - because a (finite) α -full-path may only be a prefix of a (finite or infinite) full-path
 - e.g. $E_a G p \not\Rightarrow EG p$ on $p \xrightarrow{a} p \xrightarrow{b} \bar{p}$
- In comparison, ACTL puts action conditions on temporal quantifiers,
 - e.g. $EF_{\alpha} \phi =$ “**all** paths **are** α -paths until they reach ϕ ”
 - Not adequate for our purpose

Finite Paths

Unlike classical definitions of model-checking, we allow **finite full-paths**

- Even with infinite full-paths, we would have finite α -full-paths anyway
- The semantics of CTL (and thus ARCTL) generalizes nicely
 - This is not new
- In particular, $\pi \models X \phi$ iff $|\pi| \geq 1$ $\wedge \pi(1) \models \phi$
 - $E_\alpha X \phi$ xor $A_\alpha X \neg \phi$ xor $\neg E_\alpha X true$
- $G \phi$ holds for finite α -full-paths where ϕ holds
 - We define $G^\omega \phi$ for infinite paths only

Model Checking of ARCTL

Generalizes CTL model checking:

- All ARCTL operators can be reduced to $E_\alpha X$ and $E_\alpha U$ and $E_\alpha G^\omega$
 - Additional conditions w.r.t. finite paths
 - e.g. $A_\alpha F \phi \equiv \neg E_\alpha [\neg \phi U \neg \phi \wedge \neg E_\alpha X \text{ true}] \wedge \neg E_\alpha G^\omega \neg \phi$
- Given sets of states S, S' and actions $A \in 2^A$, we define functions $eax(A, S)$, $eau(A, S, S')$ and $eag(A, S)$ capturing the semantics of those operators
 - e.g. $eau(A, S, S') = \mu Z \cdot S' \cup (S \cap eax(A, Z))$
- For any formula ϕ we can compute $\llbracket \phi \rrbracket$ using these functions
- This can all be computed using BDDs

Model Checking: details

$$eax(A, S) = \{s \mid \exists a, s' \cdot s \xrightarrow{a} s' \wedge a \in A \wedge s' \in S\}$$

$$eau(A, S, S') = \mu Z \cdot S' \cup (S \cap eax(A, Z))$$

$$eag(A, S) = \nu Z \cdot S \cap eax(A, Z)$$

$$\llbracket \mathbf{E}_\alpha \mathbf{X} \phi \rrbracket = eax(\llbracket \alpha \rrbracket, \llbracket \phi \rrbracket)$$

$$\llbracket \mathbf{A}_\alpha \mathbf{X} \phi \rrbracket = \underline{eax(\llbracket \alpha \rrbracket)} \cap \neg eax(\llbracket \alpha \rrbracket, \neg \llbracket \phi \rrbracket)$$

$$\llbracket \mathbf{E}_\alpha (\phi \mathbf{U} \phi') \rrbracket = eau(\llbracket \alpha \rrbracket, \llbracket \phi \rrbracket, \llbracket \phi' \rrbracket)$$

$$\llbracket \mathbf{A}_\alpha (\phi \mathbf{U} \phi') \rrbracket = \neg eau(\llbracket \alpha \rrbracket, \neg \llbracket \phi' \rrbracket, \neg \llbracket \phi' \rrbracket \cap (\neg \llbracket \phi \rrbracket \cup \underline{\neg eax(\llbracket \alpha \rrbracket)})) \\ \cap \neg eag(\llbracket \alpha \rrbracket, \neg \llbracket \phi' \rrbracket)$$

Finite Paths and Fairness

- CTL can be verified modulo **fairness conditions**
 - Sets of sets of states that fair traces visit infinitely often
 - LTL is reducible to CTL+fairness
- Could be extended to labelled paths and ARCTL
 - With fairness conditions on states and actions
- However, by definition, **finite full-paths are unfair**
 - A revised notion of fairness (with model checking solution) is needed
 - For further investigation ...

SMV (with Actions)

- NuSMV: symbolic model checker (IRST)
 - Rich modular modeling language
 - Properties in CTL
 - Many features, open-source
- The SMV language supports actions!
 - Named **input variables** (IVARs)
 - Unfortunately, may appear only in the **model**, **not** in the CTL **properties**

ARCTL in SMV (Take One)

First approach:

- Reduce **mixed transition structure** \mathcal{M} to **Kripke structure** $post(\mathcal{M})$
- Reduce **ARCTL formula** ϕ to plain **CTL formula** $post(\phi)$

Such that

$$(\mathcal{M}, s) \models \phi \quad \text{iff} \quad (post(\mathcal{M}), s) \models post(\phi)$$

- Check $(post(\mathcal{M}), s) \models post(\phi)$ in NuSMV
 - Does not use IVARs

Post-Projection of Actions

Principle:

- Project action propositions into the next state
 - $S' = \mathcal{A} \times \mathcal{S}$, $\mathcal{P}' = \mathcal{P}_S \cup \mathcal{P}_A$
 - $s \xrightarrow{a} s'$ becomes $(*, s) \longrightarrow (a, s')$, for any action $*$
- Reduce ARCTL to CTL accordingly, e.g.

$$\text{post}(\text{E}_\alpha \text{X } \phi) = \text{EX } (\alpha \wedge \text{post}(\phi))$$

$$\text{post}(\text{A}_\alpha \text{X } \phi) = \text{AX } (\alpha \Rightarrow \text{post}(\phi)) \wedge \underline{\text{EX } \alpha}$$

$$\begin{aligned} \text{post}(\text{A}_\alpha(\phi \text{ U } \phi')) &= \text{post}(\phi') \vee (\underline{\text{EX } \alpha} \wedge \text{post}(\phi)) \\ &\quad \wedge \text{AX } \text{A}[\underline{\text{EX } \alpha} \wedge \text{post}(\phi) \text{ U } \neg\alpha \vee \text{post}(\phi')] \end{aligned}$$

- **Erratum:** underlined terms missing in paper

Post-Projection in SMV

Both reductions have been implemented as M4 macros

- $\text{TRANS_A}(a, t) \mapsto$
 $\text{TRANS next}(a) \rightarrow (t)$
- $\text{EU_A}(a, p, q) \mapsto$
 $((p) \ \& \ \text{EX E}[(a) \ \& \ (p) \ \cup \ (a) \ \& \ (q)]) \mid (q))$
 - where a is an action formula, p, q are state formulae,
 t is a transition constraint
- User has to decide which variables are for actions (a)
and which are for states (p, q)

ARCTL in SMV (Take Two)

Second approach: extend NuSMV to provide native support for ARCTL

- Use IVARs for action variables
 - Any **valuation** of IVARs is a different action label
- Extended syntax $\mathbb{E}AX (\alpha) \phi$, $\mathbb{E}A (\alpha) [\phi \cup \phi']$, etc.
- Implementation of $eax(A, S)$, $eau(A, S, S')$ and $eag(A, S)$ on BDDs
 - As variants of existing $ex(S)$, $eu(S, S')$ and $eg(S)$
- Not done yet: generation of counter-examples

CTLK in ARCTL

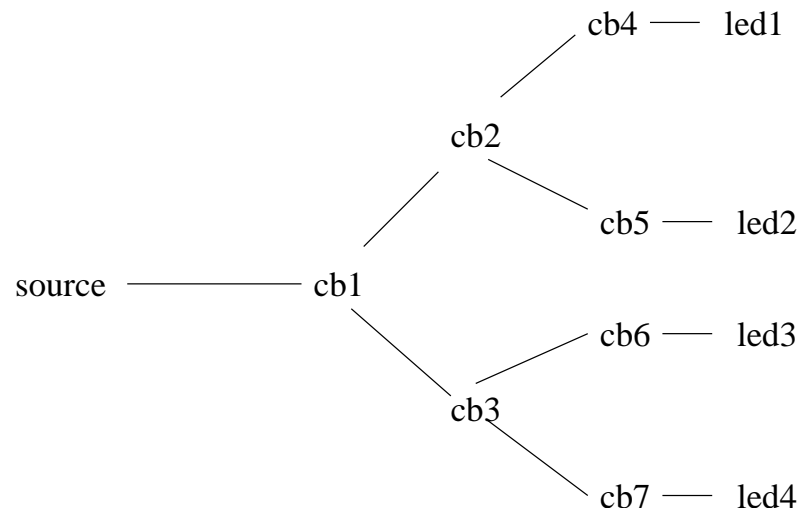
Principle: temporal transitions $s \rightarrow s'$ and epistemic accessibility relations $s \sim_{A_i} s'$ become different labels of a single labelled transition relation

- Multi-agent system (MAS) model \mathcal{M}_K translated to MTS model $F(\mathcal{M}_K)$
- CTLK property ϕ_K translated to corresponding ARCTL property $F(\phi_K)$
 - e.g. $F(K_A \phi) = A_A X (\text{reachable} \Rightarrow F(\phi))$
- Both translations implemented as M4 macros
- Model checked in SMV using either the native extension to ARCTL or further reduction to plain CTL
- Details in forthcoming paper...

Experiments 1

First experiment: verify diagnosability expressed in CTLK on *circuit-breaker* example

- Example from Livingstone model-based diagnosis system
 - cascade of circuit breakers
 - Automatically translated to SMV



Results 1

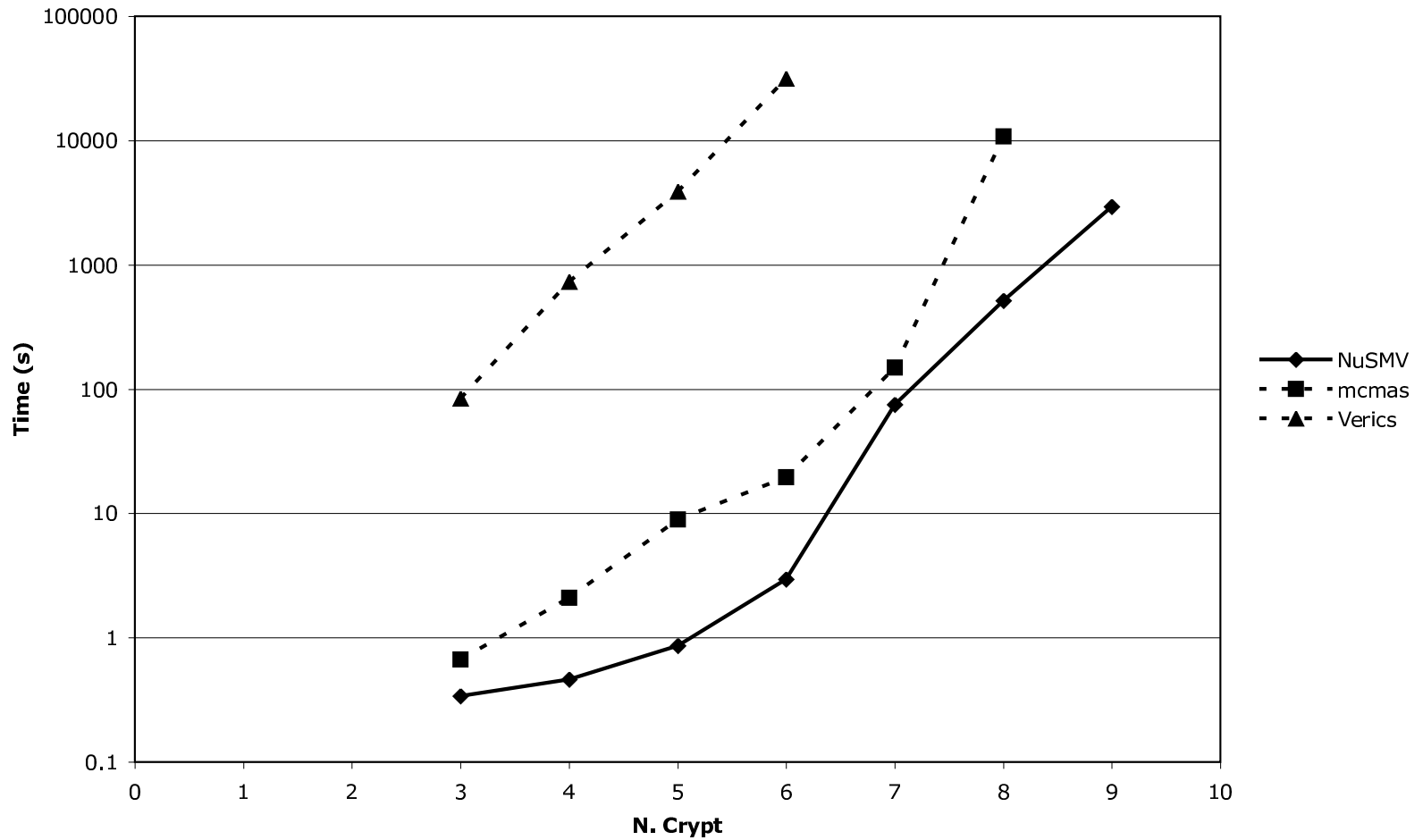
- Diagnosability property: $AG (K_D (faulty) \vee K_D (\neg faulty))$
- Used native ARCTL implementation
- Tried for various model sizes (depth of the cascade)
- Verified up to 240-bit states in less than 10 min
 - Performance similar to factory NuSMV on plain CTL properties

Experiments 2

Second experiment: verify CTLK properties of the *Dining Cryptographers protocol*

- Not diagnosis, Classical example for general epistemic properties
 - Scalable number N of agents (the Cryptographers)
- Verified protocol correctness properties
- Results are not in this paper, submitted
- 99-bit state for $N = 5$
- Comparison with Verics [Penczek et al.], MCMAS [Raimondi et al.]

Results 2



Related Work

- Other action-based logic model checkers:
 - EST [Meolic et al.] for variant of ACTL
 - SAM [Fancheti et al.] for ACTL with fixpoint operators

No state conditions, no SMV language for modeling

- Encoding of process algebras as BDDs by [Enders et al., Dsouza et al.]
- Reduction from ACTL to CTL by [de Nicola and Vaandrager]
 - In original ACTL paper
 - Adds intermediate state for every transition

Summary

- Main contributions:
 - **ARCTL**, a branching temporal logic with **action-based and state-based** atoms
 - A **reduction** *post* from ARCTL to CTL (with corresponding reduction on models)
 - A generalization of **BDD-based model-checking** from CTL to ARCTL
 - **Two implementations** of ARCTL in **SMV**: native and using *post*
- Context: **diagnosability** reduces to **CTLK**, which reduces to ARCTL
- Early but promising **experimental results**

Perspectives

- Further work:
 - Add generation of **counter-examples**
 - Study **weak variants** of ARCTL (i.e. ignoring internal actions)
 - Handle **fairness**
- Possible extensions:
 - Use SAT-based **bounded model checking** (restricts supported formulae)
 - Generalize to **game-theoretic** logics such as ATL