



Elements of a unified semantics for synchronization-free programming based on Lasp and Antidote

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LightKone and SyncFree projects



Lightweight computation for networks at the edge

- LightKone H2020 project (2017-2019) lightkone.eu
 - Lightweight computation for networks at the edge
 - Partners: UCL, UPMC/INRIA, INESC TEC/UMinho, TUKL, NOVA ID/UNL, Scality, Gluk, UPC/Guifi, Stritzinger



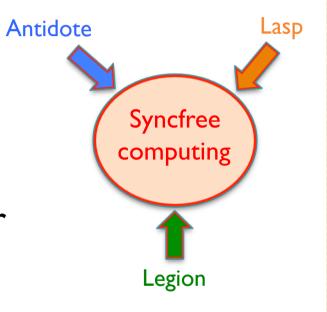
SyncFree FP7 project (2013-2016) syncfree.lip6.fr

- Large-scale computation without synchronisation
- Partners: INRIA, Basho, Trifork, Rovio, UNL, UCL, Koç, TUKL



Three systems from SyncFree

- Lasp provides dataflow composition of CRDTs
- Antidote provides causal transactional CRDT storage
- Legion provides peer-to-peer CRDT interaction between clients



\Rightarrow Each explores a different part of the space



There can be only one!

– Connor MacLeod, Highlander (1986)



There can be only one semantics! (*)

– Prof. Dr. Ir. Connor MacLeod, Hochländer (1986)

(*) Es kann nur eine Semantik geben!



Lasp and Antidote

- Lasp
 - Deterministic dataflow functional semantics
 - Graph of CRDTs connected by operations
 - Resilient communication with hybrid gossip targeting unreliable networks (e.g., edge networks)
- Antidote
 - Georeplicated data store with low latency and high availability
 - Transactional causal+ consistency on CRDTs
- Both based on CRDTs
 - Both provide consistency with weak synchronization
 - Both tolerate partitioning and message reordering

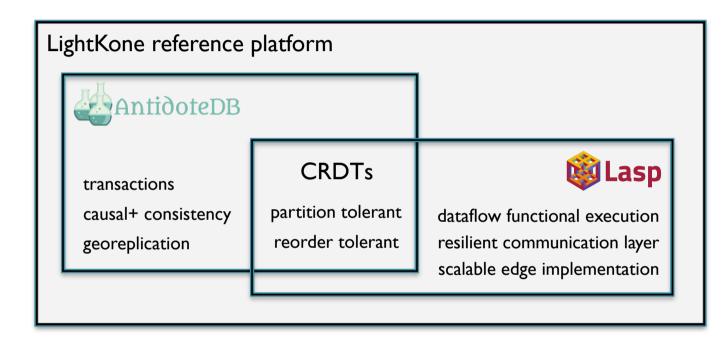


Combining Lasp and Antidote

- Both are distributed programming models based on weak synchronization
- Lasp and Antidote were invented separately
 - Both use CRDTs as their data structures
 - Both provide important functionality
 - But they have very different implementations
- We would like to combine them
 - Define one semantics that can express both
 - Allow the implementations to interoperate correctly



The LightKone reference platform



- Reference platform defined by the unified semantics
- Antidote and Lasp are partial implementations



ABSTRACT EXECUTIONS

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Abstract executions

- We describe systems in terms of events and their visibility
 - This defines observable behavior between clients and the system
 - An abstract execution is an event graph that satisfies certain correctness conditions that we explain in the next two slides
 - For full definitions see S. Burckhardt, Principles of Eventual Consistency, 2014
- Event $e \in E$: uniquely identifies objects and their operations
 - Key: key(e) ∈ Keys
 - Objects are uniquely identified by their key k
 - Operation: op(e) ∈ Ops
 - Result value: res(e) ∈ V
- Visibility relation vis \subset E×E: defines what events can see
 - We write $e_1 \leq_{vis} e_2$ when $(e_1,e_2) \in vis$
 - \circ e₁ can be observed by e₂
- Arbitration relation ar \subset E×E: breaks ties for concurrency





Data types

- Each data type T is defined by a function F_T
 - Each object k has a type defined by type(k)
- Value of an object is defined for each event e
 - Value depends on e's context, i.e., all the object's events that are visible to e (we do not represent the object state explicitly)
- Context c=ctxt(e) = (E', $op_{|E'}$, $vis_{|E'}$, $ar_{|E'}$) where E'={e' \in E | e' \leq_{vis} e}

• We can restrict the context to key k: $c_{|k} = (E, op, vis, ar)_{|k} = (E', op_{|E'}, vis_{|E'}, ar_{|E'})$ where $E' = \{e \in E | key(e) = k\}$

• Value v=
$$F_{type(key(e))}(txt(e)_{|key(e)}) \in V$$



Correct execution

- A correct execution satisfies the conditions:
 - Acyclic visibility: no cycles in vis
 - Total arbitration: ar is a total order
 - Per-object eventual consistency
 - All of an object's events are seen by all other events on that object (except for a finite number)
 - For all keys k: ∀e∈E_k. {e'∈E_k | e[≮]_{vis}e'} is finite where E_k={e | key(e)=k}
 - Correct results (definition of res)
 - $\forall e \in E. res(e) = F_{type(key(e))} (ctxt(e)_{|key(e)})$
 - Causality
 - Per-object causal consistency: ∀k: vis_{IEk} is transitive
 - Causal consistency: vis is transitive



• LASP SEMANTICS



Lasp

• Sets connected with a map:

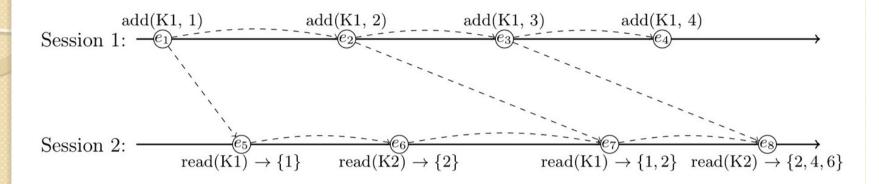


```
S1=declare(set),
bind(S1, {add, [1,2,3]}),
S2=declare(set),
map(S1, fun(X)->X*2 end, S2).
```

- Deterministic dataflow functional semantics
 - Graph of CRDTs connected by operations
 - Operations: Map, filter, fold, product, intersect, union, join
- Efficient resilient implementation
 - Ensures consistency with weak synchronization
 - Tolerates node and communication failures
 - Uses a communication layer based on hybrid gossip



Example Lasp program



 Consider a Lasp program with two objects k₁ and k₂ and a map between them:

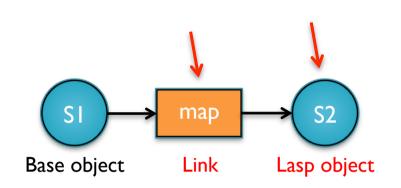
```
K1 = declare(set),
K2 = declare(set),
map(K1, fun(X) -> X*2 end, K2).
```

- Let's calculate res(e₈) = {2,4,6}
 - Set of visible events for e_8 : E'= { e_1 , e_2 , e_3 , e_5 , e_6 , e_7 }
 - res(e₈) = R(k₂, ctxt(e₈)) = (λ S→{x·2 | x∈V})(R(k₁, ctxt(e₈))) where R(k₁, ctxt(e₈)) = F_{aw-set}(ctxt(e₈)) = {1,2,3}
 - $res(e_8) = R(k_2, ctxt(e_8)) = \{2,4,6\}$



Lasp semantics

- To specify Lasp semantics, we add two concepts:
 - Lasp objects and links



- Lasp object: we partition the key space into base objects and Lasp objects
 - LaspKeys ⊂ Keys
 - Base objects have both read and update events, whereas Lasp objects have only read events
- Link: Each Lasp object k is linked from n objects
 - link(k)=([k₁,..., k_n], f)
 - $^\circ~$ The function f defines the read operation on k, which depends on $k_1, \, ..., k_n$





Lasp operations

- Lasp operations are defined by their links
 - Each Lasp operation has its own link
 - On this slide, we assume all objects have set values
- Lasp (as defined in PPDP 2015 (*)) provides:
 - Map: ([k], $\lambda \lor \rightarrow \{f(x) \mid x \in \lor\})$
 - Product: ([k₁,k₂], $\lambda \vee_1, \vee_2 \rightarrow (\vee_1 \times \vee_2)$)
 - Intersection: ([k₁,k₂], $\lambda V_1, V_2 \rightarrow (V_1 \cap V_2)$)
 - Union: ([k₁,k₂], $\lambda V_1, V_2 \rightarrow (V_1 \cup V_2)$)
 - Filter: ([k], $\lambda V \rightarrow \{x \mid x \in V \land P(x)\}$)
 - Fold: ([k], fold_{f,z}) where

LIGHTKONE

 $fold_{f,z}$ {=z and $fold_{f,z}$ ({x} \cup V)=f(x, $fold_{f,z}$ (V))

(*) Christopher Meiklejohn and Peter Van Roy. Lasp: A language for distributed, coordination-free programming. In *Principles and Practice of Declarative Programming (PPDP 2015)*. ACM, 184–195 (July 2015).

Eventual consistency of linked objects

- If a Lasp object k₁ depends on a base object k₂, then there is eventual consistency between the two objects
- First define all the objects that a Lasp object depends on (dependsOn function):
 - There are direct dependencies and transitive dependencies
 - If link(k) = ([k₁, ..., k_n], f) then $\{k_1, ..., k_n\} \subseteq dependsOn(k)$
 - If $k_a \in dependsOn(k_b)$ and $k_b \in dependsOn(k_c)$ then $k_a \in dependsOn(k_c)$
- Then all base events e are seen by all but a finite number of dependent Lasp events e':

∘ $\forall e \in E$. {e' $\in E \mid key(e) \in dependsOn(key(e')) \land e \land_{vis}e'$ } is finite

 This definition is similar to eventual consistency on one object, but here it concerns two objects



Reading from Lasp objects (1)

- Base objects can be read and updated
 - The value of a base object at event e is defined by the context of e: all events that are visible to e
 - The value can be updated because the context depends on e
- Lasp objects can only be read
 - Value of a Lasp object e is defined by the *link*, which defines a function of the base objects that the Lasp object depends on
 - No update is possible on e since the value does not depend on the context of e



Reading from Lasp objects (2)

- Result value is written res(e) for event e
 - Event e can be for a base object or a Lasp object
 - We assume res(e)=R(key(e), ctxt(e)) with R as follows
- Read from base objects
 - \circ For base objects, R is defined by F_{type} definition
 - $R(k, c) = F_{type(k)}(c_{|k})$
- Read from Lasp objects
 - For Lasp objects, R is defined by the link
 - Assume that $link(k)=([k_1, ..., k_n], f)$
 - $R(k, c) = f(R(k_1, c), ..., R(k_n, c))$



CONVERGENT CONSISTENCY (WORK IN PROGRESS)

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From eventual to convergent (1)

- So far we have defined eventual consistency for single objects and for linked (Lasp) objects
- Eventual consistency for single objects
 - All events e are seen by all but finite number of events e' on the same object
 - ∘ $\forall e \in E$: {e' ∈ E | key(e)=key(e') $\land e \not\prec_{vis} e'$ } is finite
- Eventual consistency for linked objects
 - Base events e are seen by all but finite number of dependent Lasp events e'
 - ∘ $\forall e \in E$: {e' $\in E$ | key(e) \in dependsOn(key(e')) $\land e \not\prec_{vis} e'$ } is finite
- But CRDTs do more than eventual consistency!



From eventual to convergent (2)

- Eventual consistency leaves out a key property of CRDT and Lasp execution
 - Eventual consistency says only that every event will be taken into account always after a sufficiently long time, but there is a finite interval during which the event can have erratic visibility
 - In CRDTs and Lasp, computations are always based on a strictly growing set of events (once added, an event is never forgotten)
- Lasp computations are always converging to the result
 - Every update eventually appears on all replicas
 - Each replica has a strictly growing set of updates
 - This is a monotonicity property



Convergent consistency

- Consider the definition of monotonic reads
 - $\forall e_1, e_2, e_3 \in E: e_1 \leq_{vis} e_2 \land e_2 \leq_{so} e_3 \Rightarrow e_1 \leq_{vis} e_3$
 - A (read) event once visible in a session is always visible in the session
- Convergent consistency between two objects
 - An event e of object k_1 once visible to object k_2 is always visible to k_2
 - $\circ \forall e \in \mathsf{E}_{k1}, \forall e', e'' \in \mathsf{E}_{k2} : e_{\mathsf{vis}} e' \land e'_{\mathsf{vis}} e'' \Rightarrow e_{\mathsf{vis}} e''$
- Convergent consistency for Lasp objects
 - Add the condition $k_1 \in dependsOn(k_2)$
 - If a base event is seen by a dependent Lasp event, then it is seen by all further events of the same Lasp object



Convergence and CRDTs

- Convergent consistency
 - Each event adds information permanently in a single step
- Strong eventual consistency
 - n replicas that receive the same updates (in any order) have equivalent state
 - A state-based CRDT satisfies SEC
 - An acyclic Lasp program satisfies SEC
- State-based CRDTs
 - State-based CRDT ensures SEC and CC



ANTIDOTE SEMANTICS



Antidote semantics

- Antidote provides the following guarantees
 - Acyclic visibility, total arbitration, eventual consistency
 - Causal consistency
 - Atomic visibility
 - Min snapshot
- Antidote provides a series of datatypes, such as:
 - Add-Wins Set:

```
\begin{split} F_{aw-set}(ctxt) &= F_{aw-set}(E, op, vis, ar) = \\ & \textbf{let } E' = filterResets(E, op, vis) \textbf{ in} \\ & \{x \mid (\exists a \in E'. op(a) = add(x)) \\ & \land \forall r \in E'. op(r) = remove(x) \rightarrow \exists a \in E'.op(a) = add(x) \land r \leq_{vis} a\} \end{split}
```

• Auxiliary filterResets(E, op, vis) returns events not affected by reset





Transactions

- To specify transactions, we add one concept
 - An event e is associated with a transaction t=tx(e)
- We assume all transactions are committed
 - Our model does not include time
 - We do not define isolation levels
- Atomic visibility
 - Given two transactions t_1 and t_2
 - $\forall e_1, e_1', e_2, e_2' \in E$: tx(e₁)=tx(e₁')=t₁ ∧ tx(e₂)=tx(e₂')=t₂ ⇒ e₁<_{vis}e₂ ↔ e₁'<_{vis}e₂'



Versioned store extension

- Assume that each event e has a version(e)
 - A version is a set of events
 - User can provide a version for each event, if none then version(e)= \bot
- Min snapshot
 - $\forall e, e': e' \in version(e) \Rightarrow e' \leq_{vis} e$
- Precise snapshot
 - $\forall e, e': e' \in version(e) \Leftrightarrow e' \leq_{vis} e$



CONCLUSIONS AND FURTHER WORK

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Concrete semantics

- The concrete semantics refines the abstract semantics by adding nodes, node states, and messages between nodes
 - Burckhardt gives a general framework for concrete executions
 - In this framework we define node and communication failures
- Given a concrete execution, we can derive an observable history by considering events related to calls from a client
 - A history records the interactions between clients and the system
 - An abstract execution is a history that satisfies the correctness conditions given previously
 - If the observable history can be extended to a valid abstract execution (with vis and ar), then the concrete execution is correct
- With this approach, we can prove that Lasp and Antidote protocols satisfy the abstract semantics





Conclusions

- We now have a first unified semantics that explains both Lasp and Antidote in a single framework
 - This is a step toward a general-purpose semantics for synchronizationfree programming
 - In further development of both Lasp, Antidote, and Legion we will commit to respecting this semantics
- Much work remains to be done
 - We have an abstract execution semantics that explains the observable behavior, but does not model distribution or failure
 - We need to extend this to a concrete semantics that understands nodes and their interactions
 - For continued work on the programming model, the unified semantics needs to be extended with programming concepts such as modularity and functional abstraction



• ADDITIONAL SLIDES



Session guarantees

- We assume a session order so ⊂ E×E that orders events from the same session
 - $\circ e_1 \leq e_2$ if e_1 was submitted before e_2 in the same session
- We distinguish read and write operations
 - isRead(e) and isWrite(e) predicates
- Read Your Writes
 - $\circ \ e_1 \leq_{so} e_2 \ \land \ isWrite(e_1) \ \land \ isRead(e_2) \rightarrow e_1 \leq_{vis} e_2$
- Monotonic Reads
 - $\circ \ e_1 \leq_{so} e_2 \ \land \ isRead(e_1) \ \land \ isRead(e_2) \rightarrow (\forall e'. e' \leq_{vis} e_1 \rightarrow e' \leq_{vis} e_2)$
- Writes Follow Reads
 - ∘ $e_1 \leq_{so} e_2 \land isRead(e_1) \land isWrite(e_2) \rightarrow (\forall e'. e' \leq_{vis} e_1 \rightarrow e' \leq_{vis} e_2)$
- General Session Guarantee

•
$$\mathbf{e_1} \leq_{\mathrm{so}} \mathbf{e_2} \rightarrow \mathbf{e_1} \leq_{\mathrm{vis}} \mathbf{e_2}$$

